

# **Convex Elicitation of Continuous Properties**

Jessica Finocchiaro & Rafael Frongillo University of Colorado, Boulder

{jessica.finocchiaro,raf}@colorado.edu





### **A QUADRATIC PROPERTY**

• Natural choice for V(r, y) is V(r, 1) = r - 1,  $V(r, 2) = \frac{1}{2} + r - r^2$ , V(r,3) = r.

 $V: \mathcal{R} \times \mathcal{Y} \to \mathbb{R}$  identifies  $\Gamma: \mathcal{P} \to \mathcal{R}$  if, for all  $r \in \overset{\circ}{\mathcal{R}}$  and  $p \in \mathcal{P}$  $\mathbb{E}_{Y \sim p}[V(r, Y)] = 0 \iff r = \Gamma(p)$ 

Steinwart et al. (2014) and Lambert (2018) show identifiable  $\iff$  elicitable for continuous, nowhere-locally-constant, real-valued properties.

## RESULTS

**Theorem 1: Elicitable**  $\iff$  **Convex elicitable** For  $\mathcal{P} = \Delta(\mathcal{Y})$ , let  $\Gamma : \mathcal{P} \to \mathcal{R}$  be a continuous, nowhere-locally-

constant property which is identified by a bounded and oriented V:  $\mathcal{R} \times \mathcal{Y} \to \mathbb{R}$ . If  $\mathcal{F} = \{V(\cdot, y)\}_{y \in \mathcal{Y}}$  satisfies Condition 1 (below), then  $\Gamma$ is convex elicitable.

# **PROOF INTUITION**

- $L(r, y) = \int_0^r \lambda(x) V(x, y) dx$  elicits  $\Gamma$  for  $\lambda : \mathcal{R} \to \mathbb{R}_{>0}$
- -Steinwart et al. (2014) and Lambert (2018)
- If  $\lambda(r)V(r, y)$  is increasing in  $\mathcal{R}$  for all  $y \in \mathcal{Y}$ , then  $\mathbb{E}_p L(r, Y)$  is a convex combination of convex functions.



## **CONSTRUCTING** $\lambda$

- $L(r, y) = \int_0^r \lambda(x) V(x, y) dx$  elicits  $\Gamma$  given weight function  $\lambda : \mathcal{R} \to \mathbb{R}_{>0}$ .
- Design  $\lambda(r)$  so that  $\lambda(r)V(r, y)$  increasing in r for each  $y \in \mathcal{Y}$
- -Find bounds on h.
- Search over "simple" class of functions and select h that fits bounds
- What are the conditions on  $\{V(r, y)\}_{y \in \mathcal{Y}}$  so that we can design  $\lambda$  where the above is true?

Consider the following three simple Conditions: **Condition 1'.**<sup>1</sup> Every  $f \in \mathcal{F}$  is continuously differentiable. **Condition 2'.** Each  $f \in \mathcal{F}$  has a single zero, and moves from negative to positive.

**Condition 3'.** When f > 0 > g, the ratio g/f is increasing.

# **TWO OUTCOMES**

• Consider f > 0 > g

 $\lambda(r) = (-f(r)g(r))^{-1/2}.$ 

#### Then

 $(\lambda f)(r) = \sqrt{-f(r)/g(r)} \qquad (\lambda g)(r) = \sqrt{-g(r)/f(r)}$ 

• Focus on the "most decreasing" and "least increasing" functions.

## **EXAMPLES**

$$\lambda(r) = \exp\left(\int_0^r h(r)dr\right)$$

## **SCORING RULE MARKETS**

- Lambert et al. (2008) generalizes the prediction market framework to Scoring Rule Market (SRM).
- Given loss L(r, y) and initial central prediction  $r_0$ , each trader updates the central prediction  $r_{t-1} \rightarrow r_t$ , and suffers loss  $L(r_t, y) - L(r_{t-1}, y)$ .
- Abernethy and Frongillo (2011) and Frongillo and Waggoner (2018)
- -Tractable Trade
- -Bounded Trader Budget
- Which properties have SRMs following these axioms? Essentially every continuous real-valued property over finite outcomes.

# **FUTURE WORK**

- Relaxing our conditions
- Strongly convex losses

#### **BETA FAMILIES (BUJA ET AL. (2005))**

$$\begin{split} V(r,y) &= r^{\alpha-1}(1-r)^{\beta-1}(r-y), \ L(r,y) = \int_0^r z^{\alpha-1}(1-z)^{\beta-1}(z-y)dz \\ \bullet \text{ Log loss } (\alpha = \beta = 0) \text{ and squared loss } (\alpha = \beta = 1). \\ \bullet \lambda(r) &= r^{1/2-\alpha}(1-r)^{1/2-\beta} \text{ yields:} \end{split}$$

$$V'(r, y) = r^{1/2}(1 - r)^{1/2}(r - y)$$
  
$$L'(r, y) = \arcsin(\sqrt{|y - r|}) - \sqrt{r(1 - r)}$$

• Infinite outcomes

• Vector-valued properties

#### Summary

- Elicitable  $\iff$  convex elicitable
- "Monotonize" the identification and integrate

• Essentially every continuous, real-valued property has a SRM that can be efficiently computed and allows players with arbitrarily small budget to participate in the market.

This project was funded by National Science Foundation Grant CCF-1657598.

<sup>&</sup>lt;sup>1</sup>Relaxed in the paper to allow for nondifferentiable points.